

(1)

9/10/2016

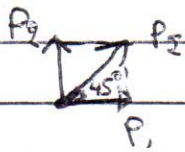
Άσκηση Διαγωνίσματος Γ Λυκείου

Θέση Α: 1→β, 2→β, 3→β, 4→δ, 5→δ, 6→α, 7→α,

8: α-ζ, β-ζ, γ-η, δ-ζ, ε-η

Θέση Β: Β1→β

$$\omega_2 = \omega_1 + \frac{90}{100} \omega_1 \Rightarrow \omega_2 = 1.9 \omega_1 \Rightarrow \frac{\omega_2}{\omega_1} = 1.9 \Rightarrow \frac{\omega_2}{\omega_1} > 1 \quad (1)$$



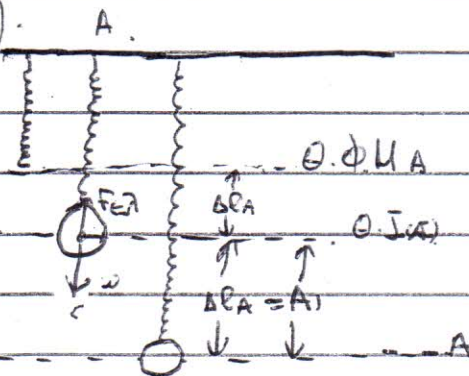
$$\cos \theta = \frac{P_2}{P_1} \Rightarrow \cos 45 = \frac{P_2}{P_1} \Rightarrow P_1 = P_2 = \rho \omega_1 v_1 = \omega_1 \rho v_1$$

$$\Rightarrow \frac{v_1}{v_2} = \frac{\omega_2}{\omega_1} \xrightarrow{(1)} \boxed{\frac{v_1}{v_2} > 1}$$

B.9.1 → (8) $k_A = 4k_B \Rightarrow \mu \cdot \omega_A^2 = 4 \cdot \mu \cdot \omega_B^2 \Rightarrow \omega_A = 2\omega_B \quad (1)$

$A_1 = \Delta l_A$ $A_2 = \Delta l_A$ αφα $\frac{v_{max}}{v_{Bmax}} = \frac{\omega_A \cdot \Delta l_A}{\omega_B \cdot \Delta l_A} \stackrel{(1)}{=} \frac{2\omega_B}{\omega_B} = 2$

B.9.9 → (6)

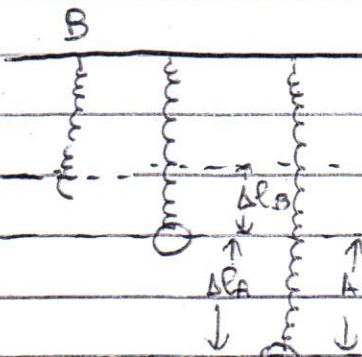


Θ. I(A): ΣF=0 ⇒ $\Delta l_A = \frac{m \cdot g}{k_A}$

$\Delta l_k = \frac{m \cdot g}{4k_B}$

$\Delta l_{maxA} = \Delta l_A + \Delta l_k \Rightarrow$

$$\boxed{\Delta l_{maxA} = \frac{m \cdot g}{4k_B}} \quad (1)$$



Θ. I(B): ΣF=0 ⇒ $\Delta l_B = \frac{m \cdot g}{k_B}$

$\Delta l_{maxB} = \Delta l_B + \Delta l_A \Rightarrow$

$$\boxed{\Delta l_{maxB} = \frac{5m \cdot g}{4k_B}} \quad (2)$$

$$\frac{v_{elAmax}}{v_{elBmax}} = \frac{\frac{1}{2} k_A \cdot \Delta l_{maxA}^2}{\frac{1}{2} k_B \cdot \Delta l_{maxB}^2} \Rightarrow \frac{v_{elAmax}}{v_{elBmax}} = \frac{\frac{1}{2} \cdot 4k_B \cdot \frac{m^2 g^2}{16 k_B^2}}{\frac{1}{2} \cdot k_B \cdot \frac{25 m^2 g^2}{16 k_B^2}} \Rightarrow \frac{v_{elAmax}}{v_{elBmax}} = \frac{16}{25}$$

B.3.1. → (6) $\omega = \frac{\Delta\phi}{\Delta t} \Rightarrow \omega = \frac{\frac{7\pi}{3} - \pi}{\frac{\pi}{15} - \frac{\pi}{30}} \Rightarrow \boxed{\omega = 10 \text{ rad/s}}$

Ka1 $\Delta\phi = \omega \cdot \Delta t \Rightarrow \phi_{t=2} - \phi_0 = \omega (t_{t=2} - t_0) \Rightarrow$
 $\pi - \phi_0 = 10 \cdot \frac{\pi}{30} \Rightarrow \boxed{\phi_0 = \frac{9\pi}{3} \text{ rad}}$

B.3.9 → (9) $T = \frac{2\pi}{\omega} \Rightarrow \boxed{T = \frac{\pi}{5} \text{ sec}}$

B.4.1 → (8) $\omega_1 = \omega, \omega_2 = 2\omega, \frac{4T_1}{4} = \frac{8T_2}{4} \Rightarrow T_1 = 2T_2 \Rightarrow \boxed{\omega_2 = 2 \cdot \omega_1}$ (1)

$U_{\max 1} = 2U_{\max 2} \Rightarrow \omega_1 \cdot A_1 = 2 \cdot \omega_2 \cdot A_2 \stackrel{(1)}{\Rightarrow} \omega_1 \cdot A_1 = 2 \cdot 2\omega_1 \cdot A_2 \Rightarrow \boxed{A_1 = 4A_2}$ (2)

$\frac{F_{\max 1}}{F_{\max 2}} = \frac{-D_1 \cdot A_1}{-D_2 \cdot A_2} = \frac{\omega_1^2 \cdot A_1}{\omega_2^2 \cdot A_2} \stackrel{(1)}{=} \frac{\omega_1^2 \cdot 4A_2}{(2\omega_1)^2 \cdot A_2} = \frac{1}{2}$

Θ.6.9 Γ: (1) $S = \frac{3A}{2} = \frac{6}{10} = \frac{3A}{2} \Rightarrow \boxed{A = 0.4 \text{ m}}$

$\Delta t = \frac{T}{2} \Rightarrow \boxed{T = 0.2 \text{ s}} \Rightarrow \boxed{\omega = 10\pi \text{ rad/s}}$
 $x = A \cdot \cos(\omega t + \phi_0) \stackrel{t=0}{x=\frac{A}{2}} \Rightarrow \frac{A}{2} = A \cdot \cos \phi_0 \Rightarrow \cos \phi_0 = \frac{1}{2} \Rightarrow \phi_0 = \frac{\pi}{6}$
 $\phi_0 = 2k\pi + \frac{\pi}{6}$
 $\phi_0 = \frac{\pi}{6} \text{ rad}$
 $\phi_0 = 2k\pi + \pi - \frac{\pi}{6}$
 $\phi_0 = \frac{5\pi}{6} \text{ rad}$

Δεκτι $\boxed{\phi_0 = \frac{\pi}{6} \text{ rad}}$ για $U > 0$
 $x = A \cdot \cos(\omega t + \phi_0)$
 $\boxed{x = 0.4 \cos(10\pi t + \frac{\pi}{6}) \text{ m}}$

Γ2] $a = -\omega^2 x \Rightarrow \boxed{x = \frac{\sqrt{3}}{10} \text{ m}}$ And A.D.F.T: $E = K + U \Rightarrow$

$\frac{1}{2} D A^2 = K + \frac{1}{2} D x^2 \Rightarrow \boxed{K = 13 \text{ J}}$

Γ3] $\frac{\Delta K}{\Delta t} = \frac{2F \cdot \Delta x}{\Delta t} = 2F \cdot v = -D \cdot x \cdot v \Rightarrow \frac{\Delta K}{\Delta t} = -\omega^2 x \cdot v$ (1)

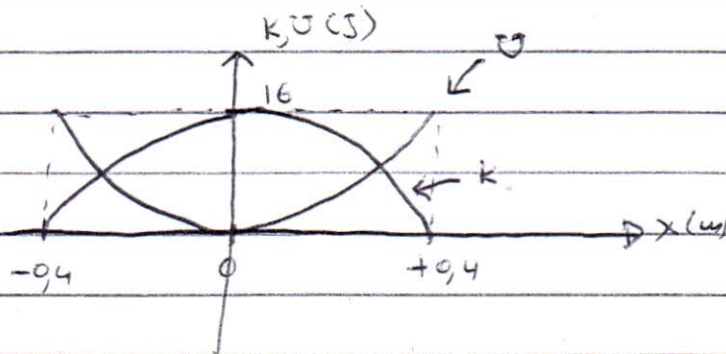
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$$t=0 \Rightarrow U = \omega \cdot A \cos(\phi_0) \Rightarrow U = 10\pi \cdot \frac{4}{10} \sqrt{3} = \boxed{U = 9\pi\sqrt{3} \text{ m/s}}$$

$$A_{\text{avg}} \frac{\Delta k(t)}{\Delta t} = \frac{q}{10} \cdot 1000 \cdot \frac{2}{10} \cdot 2\pi\sqrt{3} = -80\pi\sqrt{3} \text{ J/s}$$

$$\boxed{\frac{\Delta k}{\Delta t} = -80\pi\sqrt{3} \text{ J/s}}$$

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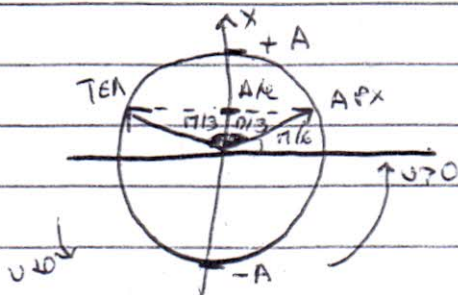


$$W_{\text{Fem}} = k_{\text{red}} - k_{\text{apx}} \Rightarrow W_{\text{Fem}} = \frac{1}{2} m \cdot U_{\text{max}}^2 - \frac{1}{2} m \cdot U^2 = 0$$

$$W_{\text{Fem}} = \frac{1}{2} \cdot \frac{q}{10} \left(\frac{10\pi \cdot 4}{10} \right)^2 - \frac{1}{2} \cdot \frac{q}{10} (9\pi\sqrt{3})^2 = 0$$

$$W_{\text{Fem}} = 16 - \frac{4 \cdot \pi^2 \cdot 3}{10} = 0 \Rightarrow \boxed{W_{\text{Fem}} = +4 \text{ J}}$$

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$$\Delta\phi = \omega \cdot \Delta t \Rightarrow$$

$$\frac{2\pi}{3} = 10\pi \cdot \Delta t \Rightarrow$$

$$\boxed{\Delta t = \frac{1}{15} \text{ s}}$$

81 a) 1)

1)

$$h = \frac{1}{2} g \cdot t^2 \Rightarrow h = \frac{1}{2} \cdot 10 \cdot \frac{\pi^2}{100} = \boxed{h = \frac{1}{2} \text{ m}}$$

$$v = g \cdot t \Rightarrow v = 10 \cdot \frac{\pi}{10} = \boxed{v = \pi \text{ m/s}}$$

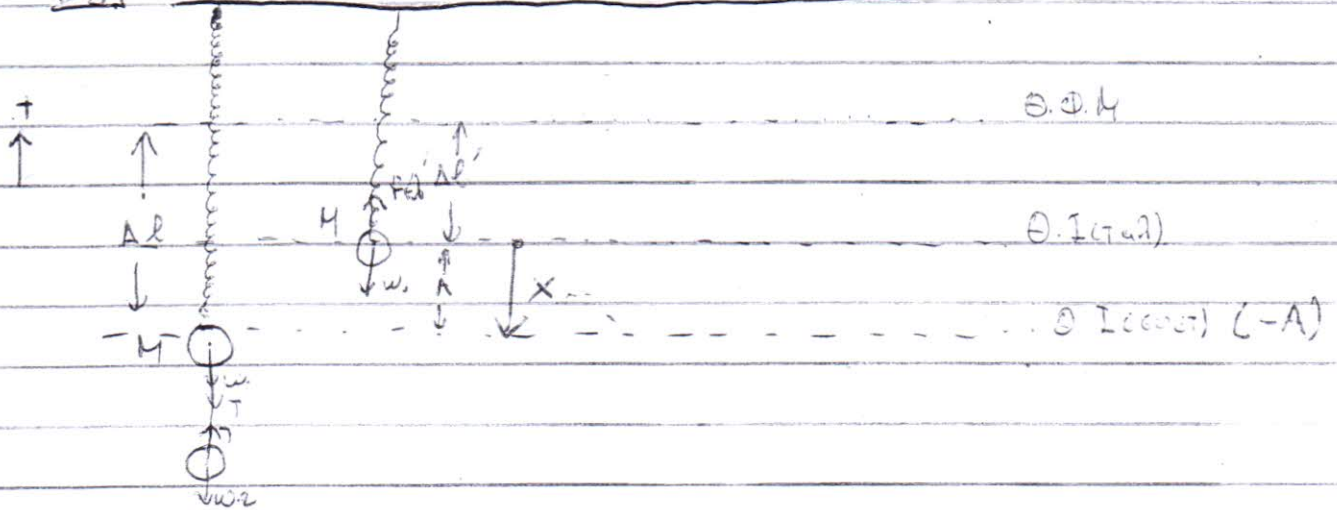
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$$t = \frac{T}{4} \Rightarrow \frac{\pi}{10} = \frac{T}{4} \Rightarrow \boxed{T = \frac{4\pi}{10} \text{ s}} \Rightarrow \boxed{\omega = 5 \text{ rad/s}}$$

$$k = 0 \Rightarrow \dots$$

$$D = k \cdot \omega^2 \Rightarrow D = 5 \cdot 95 = 0 \quad \boxed{D = 195 \text{ N/m}}$$

Δ3)



Θ.Ι ελαστικότητας: $\Delta l' = \frac{(M + m)g}{k} \Rightarrow \Delta l' = 0,5 \text{ m}$ } $A = \Delta l - \Delta l'$

Θ.Ι (σταθερά ελαστικότητας): $\Delta l' = \frac{M \cdot g}{k} \Rightarrow \Delta l' = 0,4 \text{ m}$

$\boxed{A = 0,1 \text{ m}}$

Εύρεση ϕ_0 : $t=0$: $x = A \cdot \text{yp}(\omega t + \phi_0) \xrightarrow[t=-A]{t=0} \text{yp} \phi_0 = \text{yp} \frac{3\pi}{2} \Rightarrow \boxed{\phi_0 = \frac{3\pi}{2} \text{ rad}}$

$x = A \cdot \text{yp}(\omega t + \phi_0) \Rightarrow \boxed{x = 0,1 \text{ m} \left(\sin\left(5t + \frac{3\pi}{2}\right) \right)}$ JI

Δ4) $\frac{\Sigma F}{F_{ελ}} = \frac{-D \cdot x}{k \cdot \Delta l} \xrightarrow[t=0]{x=-A} \frac{\Sigma F}{F_{ελ}} = \frac{-D \cdot (-A)}{k \cdot \Delta l} = \frac{+0,1}{0,5} \Rightarrow \boxed{\frac{\Sigma F}{F_{ελ}} = \frac{1}{5}}$

Δ5) $\frac{\Delta U}{\Delta t} = a \Rightarrow \frac{\Delta U}{\Delta t} = +a_{\max} = \omega^2 \cdot A \Rightarrow \frac{\Delta U}{\Delta t} = 95 \cdot \frac{1}{10} \Rightarrow \boxed{\frac{\Delta U}{\Delta t} = +9,5 \text{ W/s}}$

$\frac{\Delta P}{\Delta t} = \Sigma F = -D \cdot x \Rightarrow \frac{\Delta P}{\Delta t} = -195 \cdot \left(-\frac{1}{10}\right) \Rightarrow \boxed{\frac{\Delta P}{\Delta t} = 19,5 \frac{\text{kg} \cdot \text{m}}{\text{s}^2}}$

Δ6) Όταν $\Delta l = 0,45 \text{ m}$ τότε το $x = -0,05 \text{ m}$ ή $0,70$ 1^η φορά
από Α.Δ.Ε.Ι: $F = kx + U \Rightarrow U = \pm \omega \sqrt{A^2 - x^2} \Rightarrow \boxed{U = +\frac{\sqrt{3}}{4} \text{ W/s}}$

$\frac{\Delta K}{\Delta t} = D \cdot x \cdot U \Rightarrow \frac{\Delta K}{\Delta t} = -195 \cdot \left(-\frac{1}{10}\right) \cdot \frac{\sqrt{3}}{4} \Rightarrow \boxed{\frac{\Delta K}{\Delta t} = \frac{95\sqrt{3}}{16} \text{ J/s}}$